

Fundamentals of Robotics

COURSE MATERIALS

		Quantity
Hardware	YRC-Series controller with programming pendant	1
	YRC-Series-compatible robotic arm (e.g. GP8)	1
	Pneumatic gripper with I/O box	1
	Workbench and adapter plate	1
	Blocks (from I/O experiment table package)	3
	Cylinders (from I/O experiment table package)	3
	Palletizing rack with pegs	1
Software	RoboCell V10	
	MotosimEG-VRC (optional)	
Additional Materials	External source of air pressure (e.g. a portable compressor)	
	Computer	

Your robot requires a table for support and an area for performing exercises. *Intelitek Slotted Workbenches* and *Intelitek Robotic Arm Training Carts* are designed for both of these purposes.

If you have not purchased either of these products, a regular worktable can be used, provided that it can support your robotic arm. After securely mounting the robotic arm, the worktable should still contain an unused area of at least $0.5 \text{m x} \ 0.5 \text{m} \ (20'' \ \text{x} \ 20'')$ in front of the robot for the purpose of providing a space to perform lab exercises. If the worktable supporting the robot is too small for this, an additional exercise table can be placed next to the worktable.